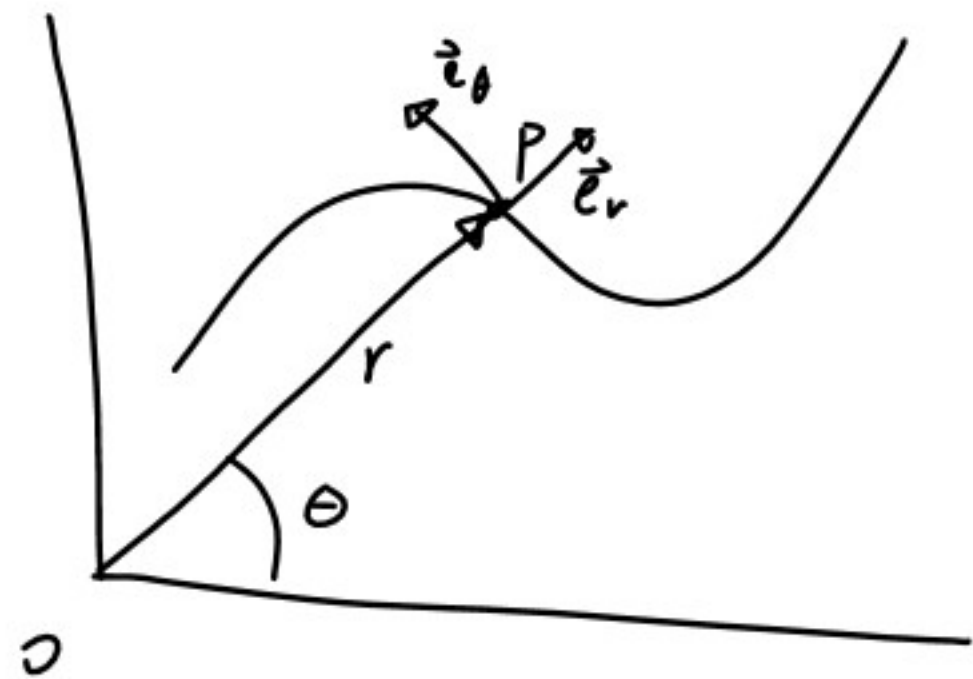


Radial and Transverse Components



\vec{e}_r and \vec{e}_θ Unit Vectors

$$\frac{d\vec{e}_r}{d\theta} = \vec{e}_\theta$$

$$\frac{d\vec{e}_\theta}{d\theta} = -\vec{e}_r$$

$$\frac{d\vec{e}_r}{dt} = \frac{d\vec{e}_r}{d\theta} \frac{d\theta}{dt}$$

$$\frac{d\vec{e}_\theta}{dt} = -\vec{e}_r \frac{d\theta}{dt}$$

$$= \vec{e}_\theta \frac{d\theta}{dt}$$

$$\dot{\vec{e}}_\theta = -\dot{\theta} \vec{e}_r$$

$$\dot{\vec{e}}_r = \dot{\theta} \vec{e}_\theta$$

$$\vec{v} = \frac{d}{dt} r \vec{e}_r = \dot{r} \vec{e}_r + r \dot{\vec{e}}_r = \dot{r} \vec{e}_r + r \dot{\theta} \vec{e}_\theta$$

$$\vec{a} = \frac{d\vec{v}}{dt} = \frac{d}{dt} \dot{r} \vec{e}_r + r \dot{\theta} \vec{e}_\theta$$

$$= \ddot{r} \vec{e}_r + \dot{r} \dot{\vec{e}}_r + \dot{r} \dot{\theta} \vec{e}_\theta + r \ddot{\theta} \vec{e}_\theta + r \dot{\theta} \dot{\vec{e}}_\theta$$

$$= (\ddot{r} - r \dot{\theta}^2) \vec{e}_r + (r \ddot{\theta} + 2\dot{r} \dot{\theta}) \vec{e}_\theta$$

$$\begin{aligned} r \dot{\theta} \dot{\vec{e}}_\theta &= r \dot{\theta} (-\dot{\theta} \vec{e}_r) \\ &= -r \dot{\theta}^2 \vec{e}_r \end{aligned}$$

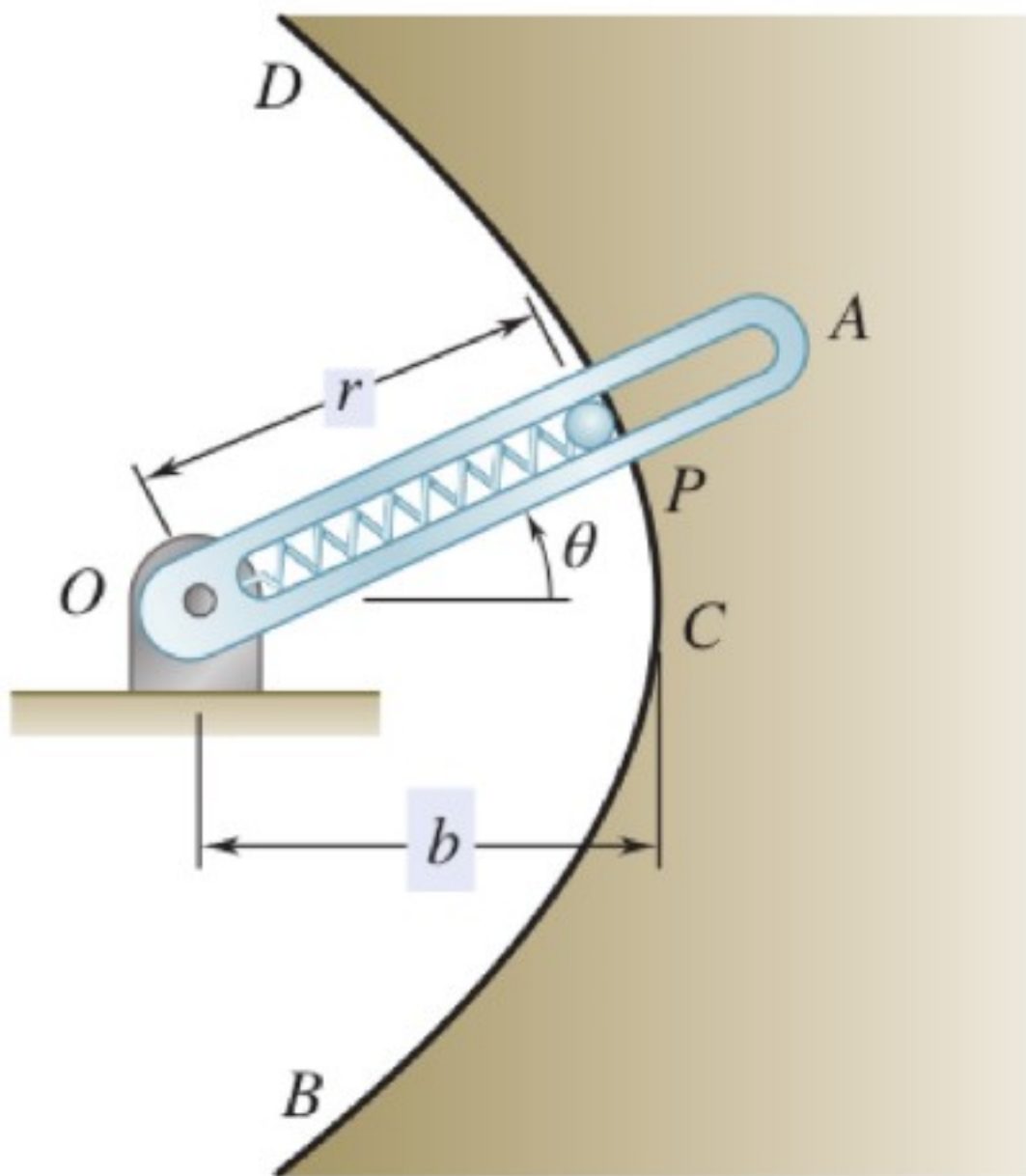
As rod OA rotates, pin P moves along the parabola BCD . Knowing that the equation of this parabola is $r = 2b/(1 + \cos \theta)$ and that $\theta = kt$, determine the velocity and acceleration of P when (a) $\theta = 0$, (b) $\theta = 90^\circ$.

$$\vec{V} = \dot{r} \vec{e}_r + r \dot{\theta} \vec{e}_\theta$$

$$= \left(\frac{2bk \sin kt}{(1 + \cos kt)^2} \right) \vec{e}_r + \frac{2b}{1 + \cos kt} k \vec{e}_\theta$$

$$\vec{V}(0) = 0 \vec{e}_r + bk \vec{e}_\theta$$

$$\vec{V}\left(\frac{90^\circ}{k}\right) = 2bk \vec{e}_r + 2bk \vec{e}_\theta$$



$$r = \frac{2b}{1 + \cos \theta}$$

$$\theta = kt$$

$$r = \frac{2b}{1 + \cos kt}$$

$$\dot{\theta} = k$$

$$\dot{r} = \frac{2bk \sin kt}{(1 + \cos kt)^2}$$

$$90^\circ = kt$$

$$t = \frac{90^\circ}{k}$$

$$\ddot{\theta} = 0$$

$$\ddot{r} = 2b \left(\frac{k^2 \cos kt}{(1 + \cos kt)^2} + \frac{2k^2 \sin^2 kt}{(1 + \cos kt)^3} \right)$$

$$\vec{a} = (\ddot{r} - r\dot{\theta}^2) \vec{e}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta}) \vec{e}_\theta$$

$$= \left(2b \left(\frac{k^2 \cos kt}{(1 + \cos kt)^2} + \frac{2k^2 \sin^2 kt}{(1 + \cos kt)^3} \right) - \frac{2bk \sin kt}{(1 + \cos kt)^2} k^2 \right) \vec{e}_r + \left(\frac{2b}{1 + \cos kt} \cdot 0 + 2 \frac{2bk \sin kt}{(1 + \cos kt)^2} k \right) \vec{e}_\theta$$

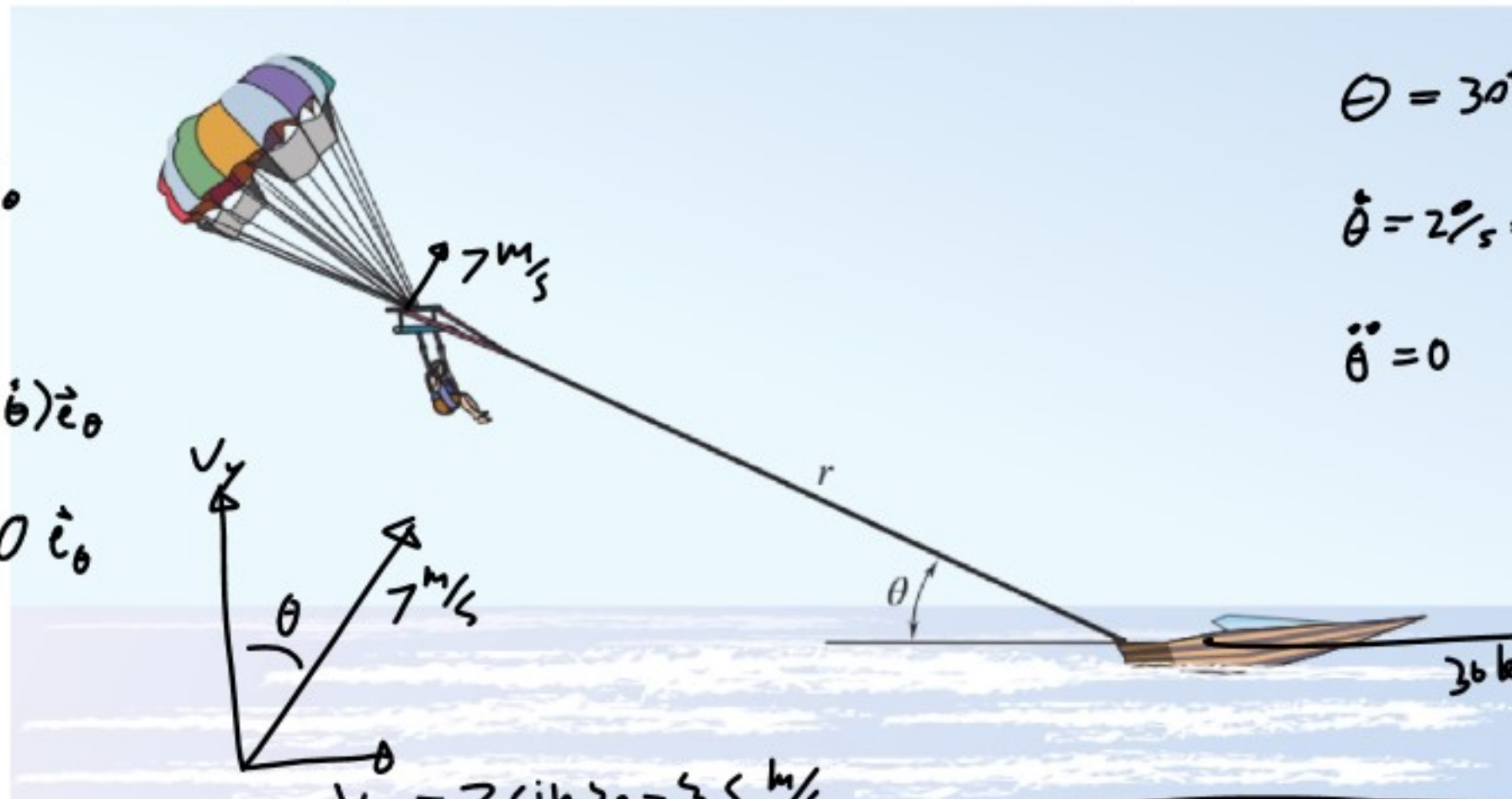
$$\vec{a}(0) = \left(2b \left(\frac{k^2}{4} \right) \right) \vec{e}_r + 0 \vec{e}_\theta$$

$$a\left(\frac{90^\circ}{k}\right) = (2b(2k^2) - 2bk^3) \vec{e}_r + (9bk^2) \vec{e}_\theta$$

During a parasailing ride, the boat is traveling at a constant 30 km/hr with a 200-m long tow line. At the instant shown, the angle between the line and the water is 30° and is increasing at a constant rate of $2^\circ/\text{s}$. Determine the velocity and acceleration of the parasailer at this instant.

$$\begin{aligned}\vec{v} &= \dot{r}\vec{e}_r + r\dot{\theta}\vec{e}_\theta \\ &= 0\vec{e}_r + 200\text{ m} \cdot 0.035 \frac{\text{rad}}{\text{s}} \vec{e}_\theta \\ &= 7\vec{e}_\theta \text{ m/s}\end{aligned}$$

$$\begin{aligned}\vec{a} &= (\ddot{r} - r\dot{\theta}^2)\vec{e}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta})\vec{e}_\theta \\ &= 200\text{ m} (0.035 \frac{\text{rad}}{\text{s}})^2 \vec{e}_r + 0\vec{e}_\theta\end{aligned}$$



$$\theta = 30^\circ = 0.52 \text{ rad} \quad r = 200 \text{ m}$$

$$\dot{\theta} = 2^\circ/\text{s} = 0.035 \frac{\text{rad}}{\text{s}} \quad \dot{r} = 0$$

$$\ddot{\theta} = 0$$

$$\begin{aligned}30 \frac{\text{km}}{\text{h}} &\left(\frac{1000\text{ m}}{1\text{ km}}\right) \left(\frac{1\text{ h}}{3600\text{ s}}\right) \left(\frac{1\text{ min}}{60\text{ s}}\right) \\ &= 8.33 \text{ m/s}\end{aligned}$$

$$v_x = 7 \sin 30 = 3.5 \text{ m/s}$$

$$v_y = 7 \cos 30 = 6.02$$

$$\vec{v}_{\text{total}} = (3.5 + 8.33)\mathbf{i} + 6.02\mathbf{j}$$