

The sprocket wheel and chain shown are initially at rest. If the wheel has a uniform angular acceleration of 90 rad/s^2 counterclockwise, determine (a) the acceleration of point A of the chain, (b) the magnitude of the acceleration of point B of the wheel after 3 s.

$$\alpha = 90 \text{ K } \frac{\text{rad}}{\text{s}^2}$$

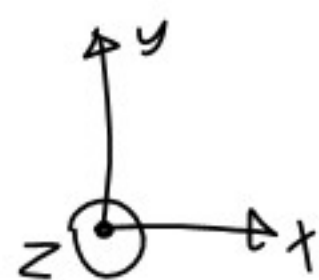
$$\omega = \omega_0 + \alpha t$$

$$\omega = \alpha t$$

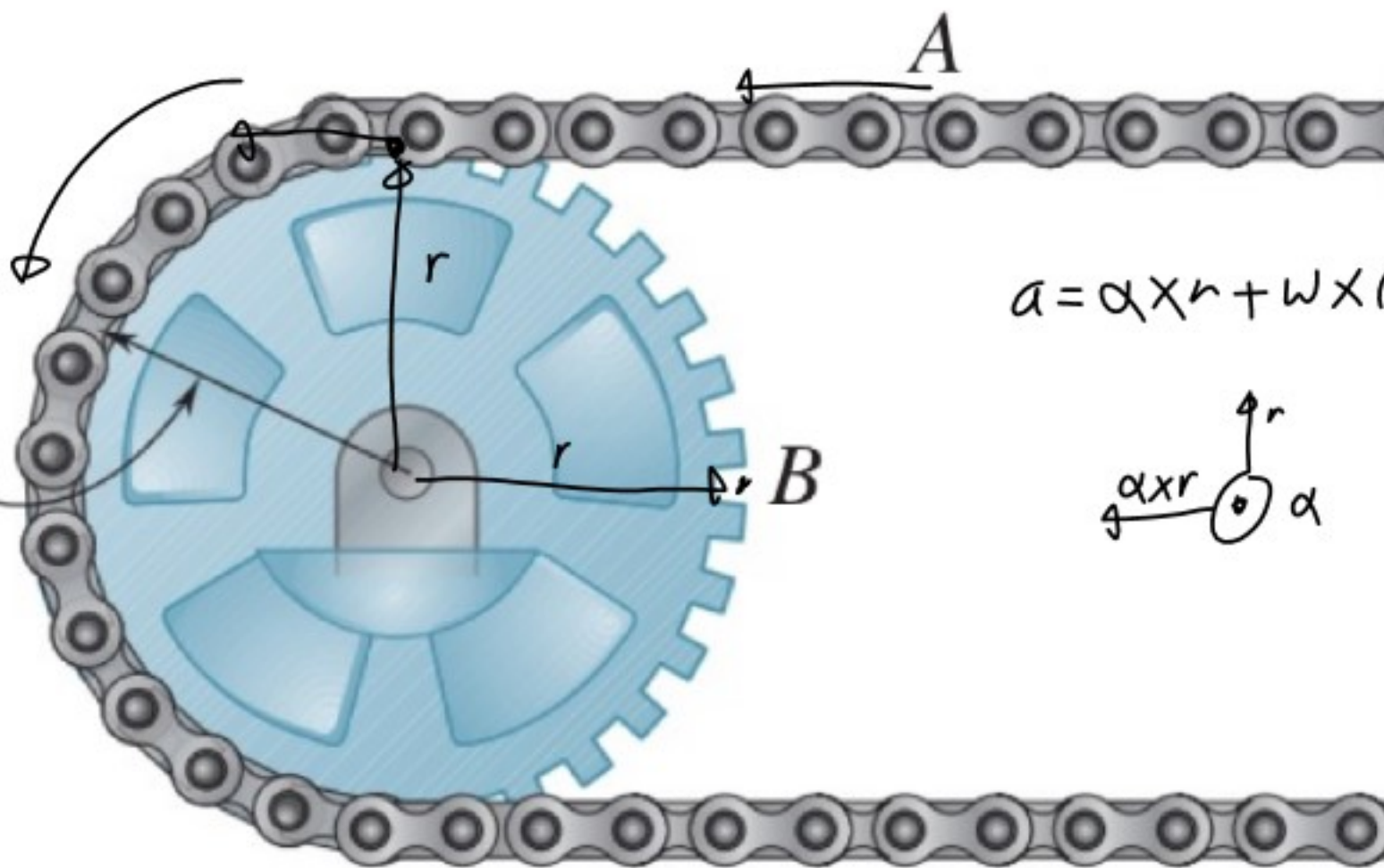
$$\omega = 90 \text{ K } 3$$

$$\omega = 270 \text{ K } \frac{\text{rad}}{\text{s}}$$

$$r = 4 \text{ j } \text{ in}$$

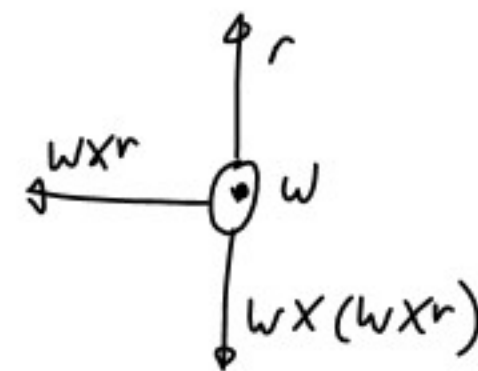


4 in.



$$v = 4 \text{ j } \text{ in}$$

$$a = \alpha \times r + \omega \times (\omega \times r)$$



$$a = \alpha \times r = \begin{vmatrix} i & j & k \\ 0 & 0 & 90 \\ 0 & 4 & 0 \end{vmatrix} \begin{vmatrix} i & j \\ 0 & 0 \\ 0 & 4 \end{vmatrix} = -4 \cdot 90 i \text{ in/s}^2 = \boxed{-360 i \text{ in/s}^2}$$

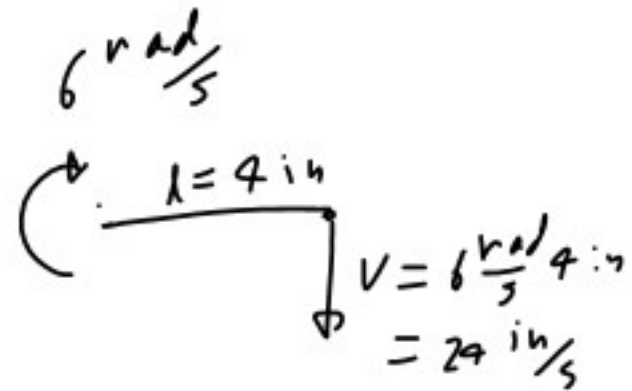
$$a = \alpha \times r + \omega \times (\omega \times r) \\ = 360 j - 291.6 \times 10^3 i \text{ in/s}^2$$

$$\sqrt{360^2 + (291.6 \times 10^3)^2} = \boxed{291.6 \times 10^3 \text{ in/s}^2}$$

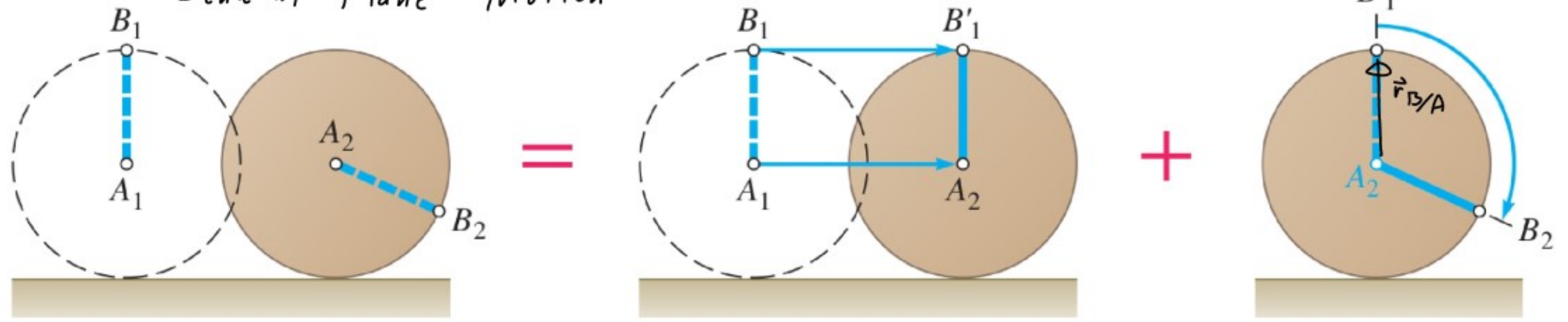
$$\alpha \times r = \begin{vmatrix} i & j & k \\ 0 & 0 & 90 \\ 4 & 0 & 0 \end{vmatrix} \begin{vmatrix} i & j \\ 0 & 0 \\ 4 & 0 \end{vmatrix} = 360 j \text{ in/s}^2$$

$$\omega \times r = \begin{vmatrix} i & j & k \\ 0 & 0 & 270 \\ 4 & 0 & 0 \end{vmatrix} \begin{vmatrix} i & j \\ 0 & 0 \\ 4 & 0 \end{vmatrix} = 4 \cdot 270 j = 1080 j \text{ in/s}^2$$

$$\omega \times (\omega \times r) = \begin{vmatrix} i & j & k \\ 0 & 0 & 270 \\ 0 & 1080 & 0 \end{vmatrix} \begin{vmatrix} i & j \\ 0 & 0 \\ 0 & 1080 \end{vmatrix} = -270 \cdot 1080 i = -291.6 \times 10^3 i \text{ in/s}^2$$



General Plane Motion



Plane motion

=

Translation with A

+

Rotation about A

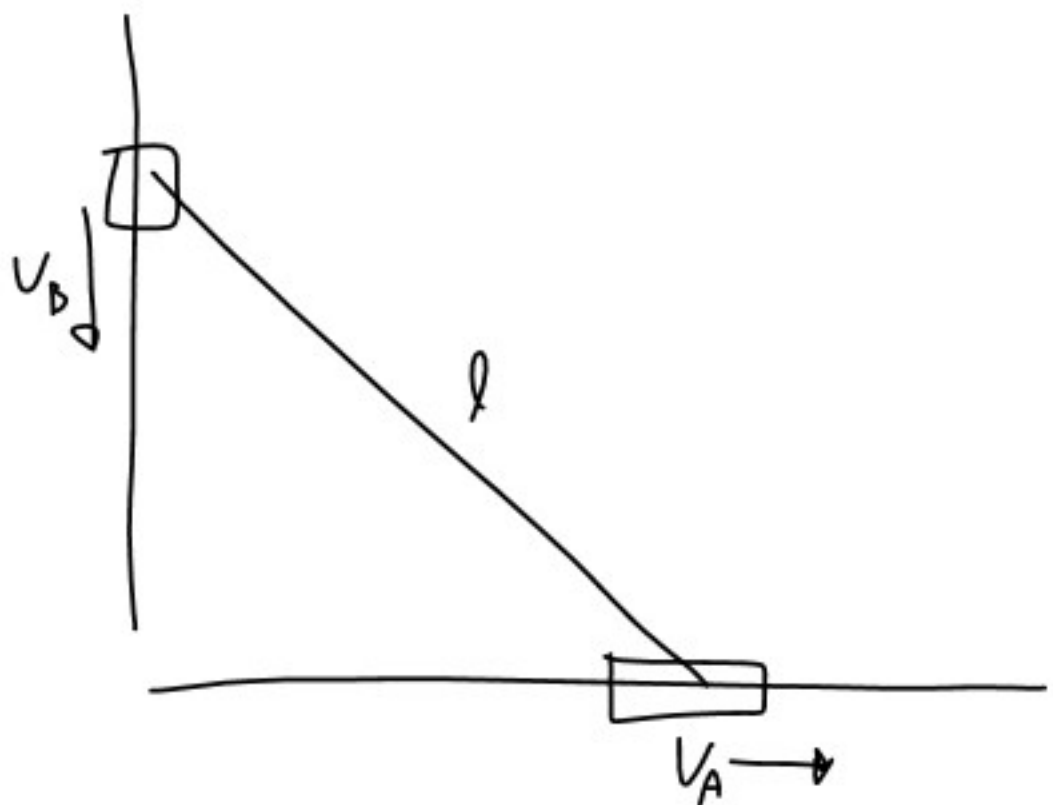
$$\vec{V}_B = \vec{V}_A + \vec{V}_{B/A}$$

$$\vec{V}_{B/A} = \vec{\omega} \times \vec{r}_{B/A} \quad 3D$$

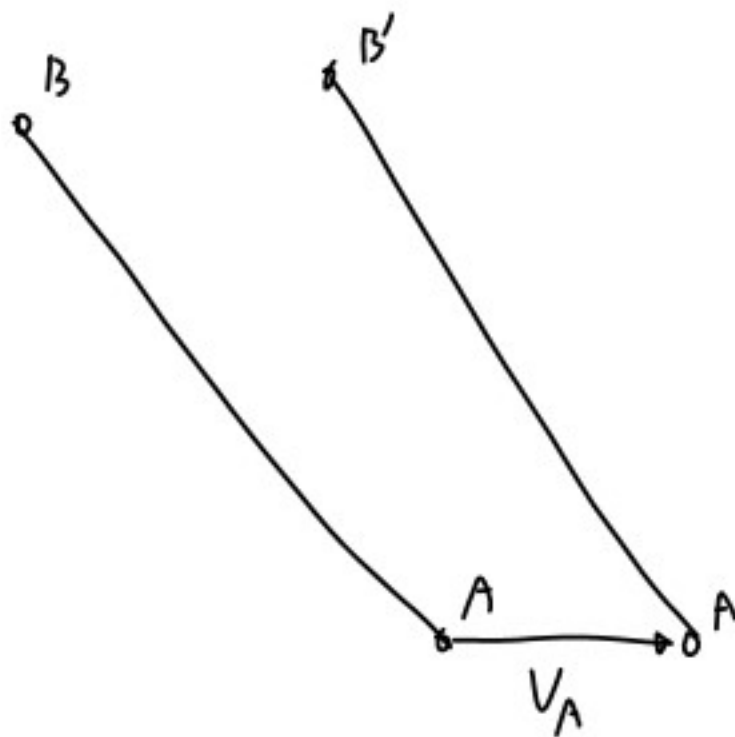
$$\vec{V}_B = \vec{V}_A + \omega \mathbf{k} \times \vec{r}_{B/A}$$

$$\vec{V}_{B/A} = \omega \mathbf{k} \times \vec{r}_{B/A} \quad 2D \quad \text{"plane motion"}$$

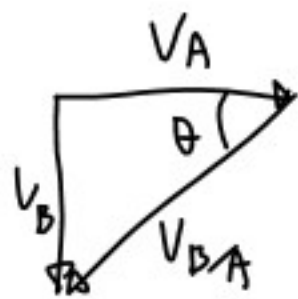
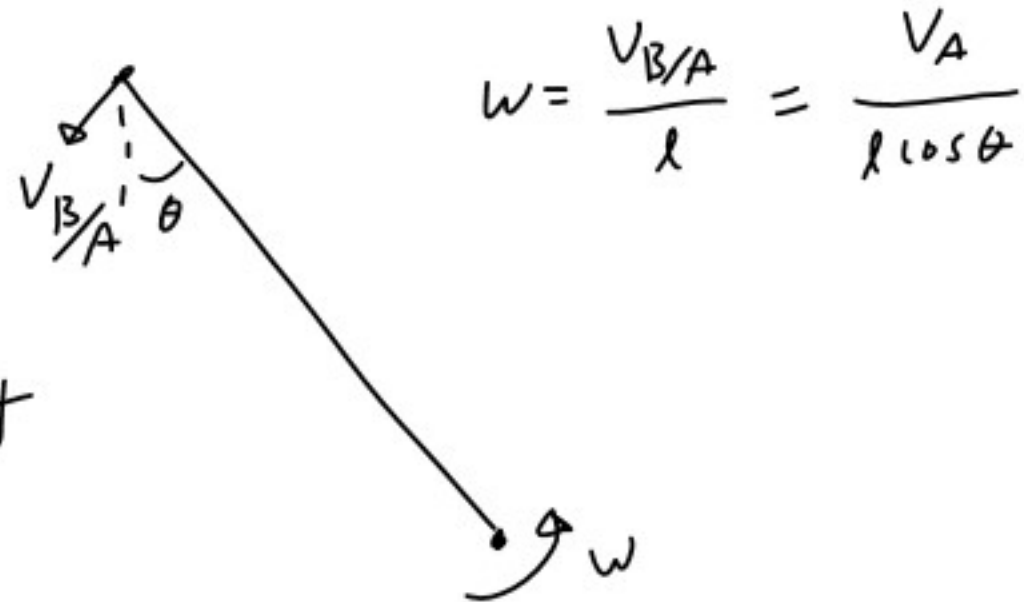
$$V_{B/A} = r\omega$$



=



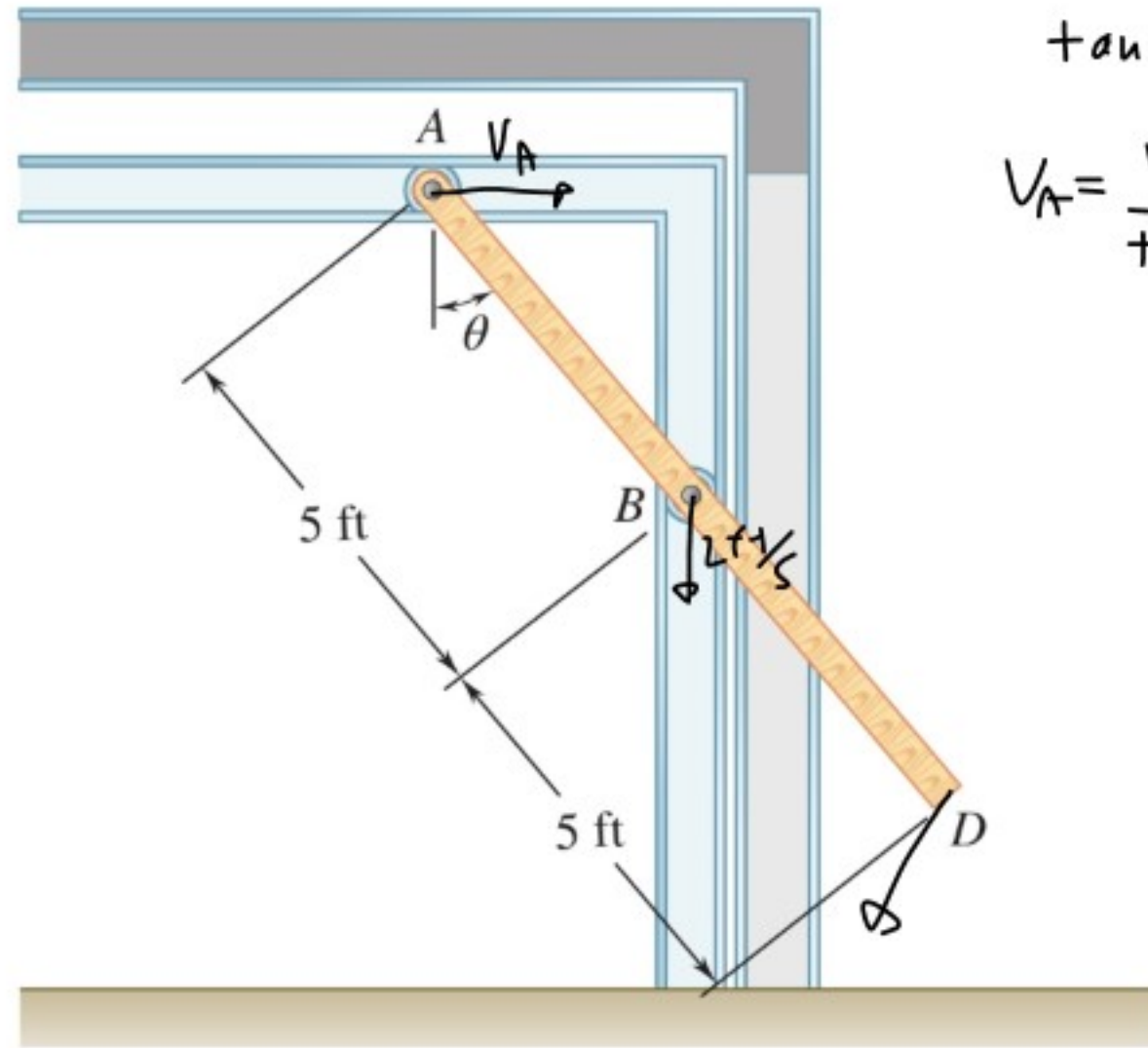
+



$$\frac{V_B}{V_A} = \tan \theta$$

$$V_{B/A} = \frac{V_A}{\cos \theta}$$

An overhead door is guided by wheels at A and B that roll in horizontal and vertical tracks. Knowing that when $\theta = 30^\circ$ the velocity of wheel B is 2 ft/s downward, determine (a) the angular velocity of the door, (b) the velocity of end D of the door.



$$\tan \theta = \frac{V_B}{V_A}$$

$$V_A = \frac{V_B}{\tan \theta}$$

$$\omega = \frac{V_A}{l \cos \theta}$$

$$\omega = \frac{V_B}{l \cos \theta \tan \theta}$$

$$= \frac{V_B}{l \cos \theta \frac{\sin \theta}{\cos \theta}}$$

$$= \frac{V_B}{l \sin \theta} = \frac{2}{5 \sin 30^\circ}$$

$$= 0.8 \text{ rad/s}$$