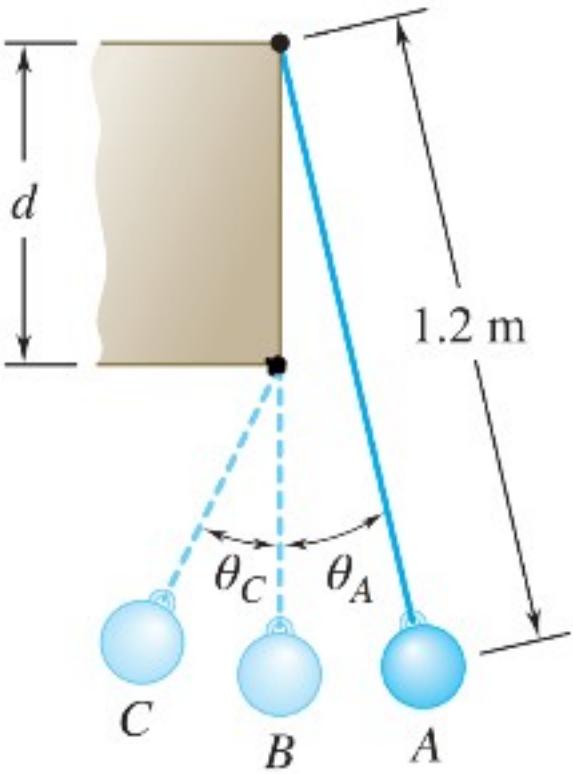


- 19.16** A small bob is attached to a cord of length 1.2 m and is released from rest when $\theta_A = 5^\circ$. Knowing that $d = 0.6$ m, determine (a) the time required for the bob to return to point A, (b) the amplitude θ_C .



$$\tau_n = 2\pi \sqrt{\frac{l}{g}}$$

$$\tau_A = 2\pi \sqrt{\frac{1.2 \text{ m}}{9.8 \text{ m/s}^2}} = 2.2 \text{ s}$$

$$t_{A \rightarrow B} = \frac{\tau_A}{4}$$

$$t_{B \rightarrow A} = \frac{\tau_A}{4}$$

$$\tau_c = 2\pi \sqrt{\frac{0.6 \text{ m}}{9.8 \text{ m/s}^2}} = 1.55 \text{ s}$$

$$t_{B \rightarrow C} = \frac{\tau_c}{4}$$

$$t_{C \rightarrow D} = \frac{\tau_c}{4}$$

$$t = t_{A \rightarrow B} + t_{B \rightarrow C} + t_{C \rightarrow D} + t_{D \rightarrow A} = \frac{\tau_A}{2} + \frac{\tau_c}{2}$$

$$= \frac{2.2 \text{ s}}{2} + \frac{1.55 \text{ s}}{2} = \boxed{1.83 \text{ s}}$$

$$\theta_A(t) = \theta_A \cos(\omega_n t)$$

$$\dot{\theta}_A(t) = -\omega_n \theta_A \sin(\omega_n t)$$

$$\dot{\theta}_{BA} = -\omega_n \theta_A$$

$$V_B = l_A \dot{\theta}_{BA}$$

$$\ddot{\theta}_{BC} = \frac{V_B}{l_C}$$

$$\dot{\theta}_C(t) = -\omega_n \theta_C \sin(\omega_n t)$$

$$-\omega_n \theta_C = \dot{\theta}_{BC} = \frac{V_B}{l_C} = \frac{l_A \dot{\theta}_{BA}}{l_C} = \frac{l_A (-\omega_n \theta_A)}{l_C}$$

$$\theta_C = \frac{l_A \omega_n \theta_A}{l_C \omega_n} = \frac{l_A \sqrt{\frac{g}{l_A}} \theta_A}{l_C \sqrt{\frac{g}{l_C}}} = \frac{l_A / \sqrt{l_A} \theta_A}{l_C / \sqrt{l_C}} = \frac{\sqrt{l_A} \theta_A}{\sqrt{l_C}}$$

$$= \frac{\sqrt{1.2} \text{ } 5^\circ}{\sqrt{0.6}} \neq 7.071^\circ$$

$$T_{A\theta_0} + U_A = T_C + U_C$$

$$mg h_A = mg h_C$$

$$h_A = h_C$$

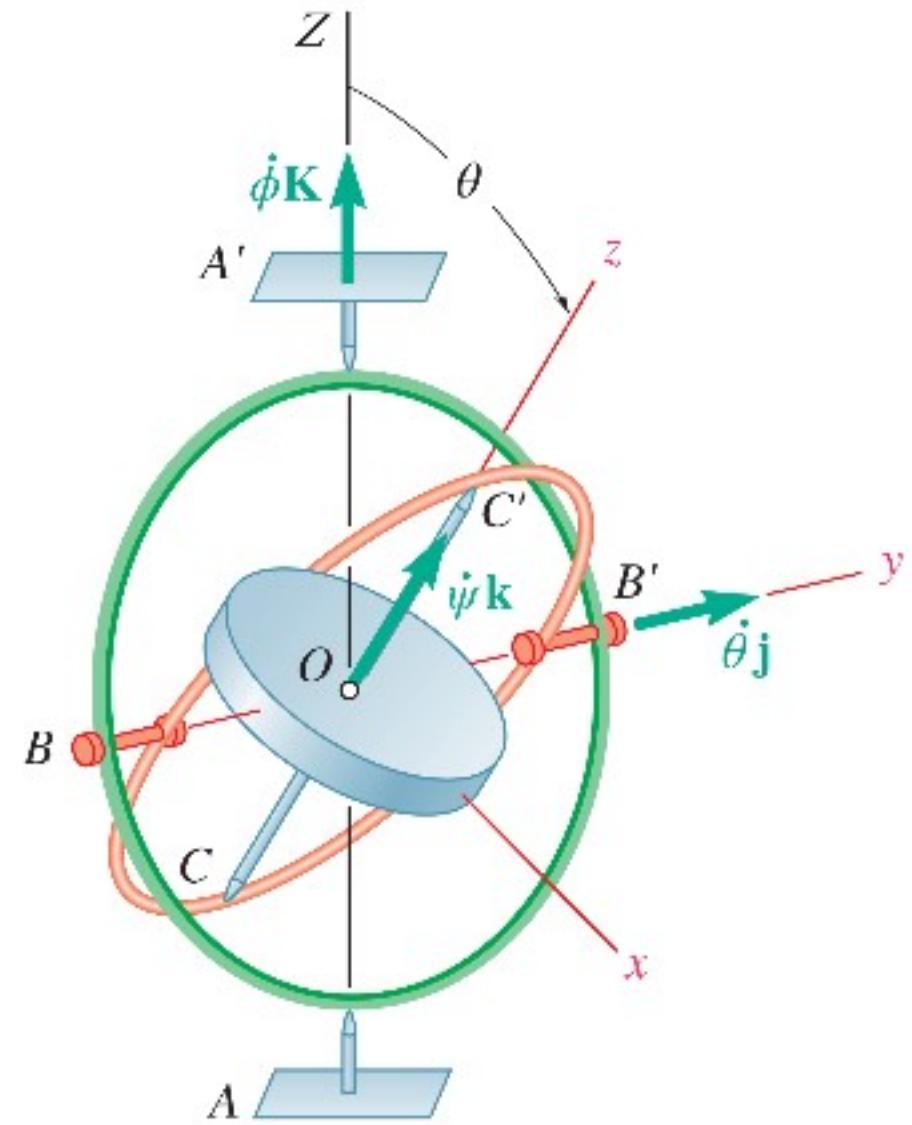
$$-1.2m \cos 5^\circ = -0.6m - 0.6m \cos \theta_C$$

$$0.6 m \cos \theta_C = 1.2 m \cos 5^\circ - 0.6 m$$

$$\cos \theta_C = \frac{1.2 \cos 5^\circ - 0.6}{0.6}$$

$$\boxed{\theta_C = 7.073^\circ}$$

Gyroscopes



$$\omega = \dot{\phi} \mathbf{k} + \dot{\theta} \mathbf{j} + \dot{\psi} \mathbf{k}$$

$$\mathbf{k} = -\sin \theta \mathbf{i} + \cos \theta \mathbf{k}$$

$$\omega = -\dot{\phi} \sin \theta \mathbf{i} + \dot{\theta} \mathbf{j} + (\dot{\psi} + \dot{\phi} \cos \theta) \mathbf{k}$$

$$H_0 = -I' \dot{\phi} \sin \theta \mathbf{i} + I' \dot{\theta} \mathbf{j} + I(\dot{\psi} + \dot{\phi} \cos \theta) \mathbf{k}$$

$$\begin{aligned}\underline{\omega} &= \dot{\phi} \mathbf{k} + \dot{\theta} \mathbf{j} \\ &= \dot{\phi} \sin \theta \mathbf{i} + \dot{\theta} \mathbf{j} + \dot{\phi} \cos \theta \mathbf{k}\end{aligned}$$

Steady Precession

$\dot{\theta}$ constant

$$\omega = -\dot{\phi} \sin \theta \mathbf{i} + \omega_z \mathbf{k}$$

$$H_1 = -I' \dot{\phi} \sin \theta \mathbf{i} + I \omega_z \mathbf{k}$$

$$\underline{\omega} = -\dot{\phi} \sin \theta \mathbf{i} + \dot{\phi} \cos \theta \mathbf{k}$$

$$\sum M_o = \mathcal{L} \times H_o$$

$$= (I\omega_z - I' \dot{\phi} \cos \theta) \hat{x} \sin \theta \hat{j}$$

$$\text{if } \theta = 90^\circ$$

$$\sum M_o = I\dot{\psi} \hat{x} \times \hat{j} = \hat{x} \times I\dot{\psi}$$

