trans.firsto First-order systems in transient response

free response $y_{\rm fr}$

1 First order systems have input-output differential equations of the form

$$\tau \frac{dy}{dt} + y = b_1 \frac{du}{dt} + b_0 u \tag{1}$$
 with $\tau \in \mathbb{R}$ called the time constant of the system. Systems with a single energy storage element—such as those with electrical or thermal capacitance—can be modeled as first-order.

2 The characteristic equation yields a single root $\lambda = -1/\tau$, so the homogeneous solution y_h , for constant $\kappa \in \mathbb{R}$, is

Yh=Ke-th

Free response

3 The free response y_{fr} of a system is its response to initial conditions and no forcing (f(t) = 0). This is useful for two reasons:

1. perturbations of the system from equilibrium result in free response and 2. from superposition, the free response can be added to a forced response to find the specific response: $y(t) = y_{fr}(t) + y_{fo}(t)$. This allows us to use tables of solutions

like Table firsto.1 to construct solutions for

systems with nonzero initial conditions with forcing. 4 The free response is found by applying initial conditions to the homogeneous solution.

With initial condition y(0), the free response is

$$y_{fr}(t) = y(0) e^{-t/\tau},$$
 (2)

which begins at y(0) and decays exponentially to zero.

Step response

5 In what follows, we develop forced response forced response y_{fo} y_{fo} solutions, which are the specific solution responses of systems to given inputs and zero zero initial conditions

initial conditions: all initial conditions set to 6 If we consider the common situation that $\mathfrak{b}_1=0$ and $\mathfrak{u}(t)=K\mathfrak{u}_s(t)$ for some $K\in\mathbb{R}$, the

7+. (+)=Kb. (1-e

The non-steady term is simply a constant

scaling of a decaying exponential. 7 A plot of the step response is shown in Figure firsto.1. As with the free response, within 5τ the transient response is less than 1% of the difference between y(0) and steady-state.

Impulse and ramp responses

0.8 Kb₀

0.6 Kb₀

0.4 Kb₀

 $0.2\,\mathrm{Kb}_0$

solution to Equation 1 is

8 The response to all three singularity inputs are included in Table firsto.1. These can be

y + v (+) = 6. (1-e-54) $y_{i} = 1 - e^{-t_{i}}$ $\dot{y}_{i} = \frac{1}{7}e^{-t_{i}}$ y z = b, ÿ, + b, y,

= b, fe - th + b, (1-e-th) = b, fe - th + b, - b, e-th $= (\frac{b_{1}}{e^{-b_{0}}})e^{-\frac{e^{-t}}{e^{-t}}} + b_{0}$ $= b_{0} - (b_{0} - \frac{b_{1}}{e^{-t}})e^{-\frac{t}{e^{-t}}}$ steady-state - forcing Kb₀u_s(t) free response $y_{fr}(t)$ forced response $y_{fo}(t)$ $y_{fr}(t) + y_{fo}(t)$

 $\textbf{Figure firsto.1:} \ \text{free and forced responses and their sum for a first order system with input} \ u(t) = Ku_s(t), \ \text{initial condition} \ y(0), \ \text{and} \ b_1 = 0.$

combined with the free response of Equation 2 using superposition. Results could be described

as bitchin'.

 $\textbf{Table firsto.1:} \ \ \text{first-order system characteristic and total forced responses for singularity inputs.} \ \ \text{The relevant differential equation is of the standard form} \ \ \tau \dot{y} + y = f.$

time (s)

$\mathfrak{u}(t)$	$\begin{aligned} & \text{characteristic response} \\ & f(t) = u(t) \end{aligned}$	total forced response y_{fo} for $t\geqslant 0$ $f(t)=b_1\dot{u}+b_0u$
$\delta(t)$	$\frac{1}{\tau}e^{-t/\tau}$	$\frac{b_1}{\tau}\delta(t) + \left(\frac{b_0}{\tau} - \frac{b_1}{\tau^2}\right)e^{-t/\tau}$
$\mathfrak{u}_s(t)$	$1-e^{-t/\tau}$	$b_0 - \left(b_0 - \frac{b_1}{\tau}\right) e^{-t/\tau}$
$\mathfrak{u}_r(t)$	$t - \tau (1 - e^{-t/\tau})$	$b_0 t + (b_1 - b_0 \tau)(1 - e^{-t/\tau})$

Example trans.firsto-1

re: RC-circuit response the easy way

Consider a parallel RC-circuit with input current $I_S(t) = 2u_s(t)$ A, initial capacitor voltage $v_C(0) = 3$ V, resistance R = 1000 Ω , and capacitance C = 1 mF. Proceeding with the usual analysis would produce the io differential equation

$$C\frac{d\nu_C}{dt} + \nu_C/R = I_S.$$

Use Table firsto.1 to find $v_C(t)$.

$$U = I_{s} = 2 u_{s}$$

$$y = V_{c}$$

$$C \frac{dv_{c}}{dt} + \frac{V_{c}}{R} = I_{s}$$

$$RC \frac{dv_{c}}{dt} + V_{c} = RI_{s}$$

$$Y = RC \qquad f(t) = 2R u_{s}(t)$$

$$Y_{tr} = y(0)e \qquad \qquad y(0) = V_{c}(0) = 3$$

$$= 3e^{-t/\tau}$$

$$Y_{ch} = 1 - e^{-t/\tau}$$

$$Y_{to} = 2R(1 - e^{-t/\tau})$$

$$Y(t) = Y_{tr}(t) + Y_{to}(t)$$

$$= 3e^{-t/\tau} + 2R(1 - e^{-t/\tau})$$

= 2R + (3-2R) e - tx