

imp.2port Impedance with two-port elements

- The two types of energy transducing elements, transformers and gyrators, "reflect" or "transmit" impedance through themselves, such that they are "felt" on the other side.
- For a transformer, the elemental equations are

$$V_2(t) = V_1(t)/TF \quad \text{and} \quad \mathcal{F}_2(t) = -TF\mathcal{F}_1(t), \quad (1)$$

the Laplace transforms of which are

$$V_2(s) = V_1(s)/TF \quad \text{and} \quad \mathcal{F}_2(s) = -TF\mathcal{F}_1(s). \quad (2)$$

- If, on the 2-side, the input impedance is Z_3 , as in Fig. 2port.1, the equations of Eq. 2 are subject to the continuity and compatibility equations

$$V_2 = V_3 \quad \text{and} \quad \mathcal{F}_2 = -\mathcal{F}_3. \quad (3)$$

Substituting these into Eq. 2 and solving for V_1 and \mathcal{F}_1 ,

$$V_1 = TFV_3 \quad \text{and} \quad \mathcal{F}_1 = \mathcal{F}_3/TF. \quad (4)$$

The elemental equation for element 3 is $V_3 = \mathcal{F}_3 Z_3$, which can be substituted into the through-variable equation to yield

$$\mathcal{F}_1 = \frac{1}{Z_3 TF} V_3$$

- Working our way back from V_3 to V_1 , we apply the compatibility equation $V_2 = V_3$ and the elemental equation $V_2 = V_1/TF$, as follows:

$$\begin{aligned} \mathcal{F}_1 &= \frac{1}{Z_3 TF} V_2 \\ &= \frac{1}{Z_3 TF^2} V_1 \end{aligned}$$

Solving for the effective input impedance Z_1 ,

$$Z_1 \equiv \frac{V_1(s)}{\mathcal{F}_1(s)} \quad (5)$$

$$= TF^2 Z_3. \quad (6)$$

- For a gyrator with gyrator modulus GY , in the configuration shown in Fig. 2port.2, a similar derivation yields the effective input impedance Z_1 ,

$$Z_1 = GY^2/Z_3. \quad (7)$$

transformers
gyrators

transformer

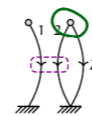


Figure 2port.1:

effective input impedance



Figure 2port.2:

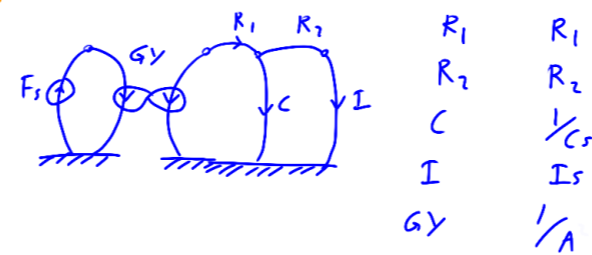
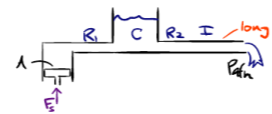
gyrator

effective input impedance

Example imp.2port-1

re: input impedance of fluid system with transducer

Draw a linear graph of the fluid system. What is the input impedance for an input force to the piston?



$$Z_{R_2 I} = R_2 + I_s$$

$$Z_{R_2 I C} = \frac{1}{\frac{1}{R_2 + I_s} + C_s} = \frac{R_2 + I_s}{1 + CR_2 s + CI_s^2}$$

$$Z_3 = R_1 + \frac{R_2 + I_s}{1 + CR_2 s + CI_s^2}$$

$$Z_1 = GY^2 \left(R_1 + \frac{R_2 + I_s}{1 + CR_2 s + CI_s^2} \right)$$

$$\frac{V_s(s)}{F_s(s)} = \frac{1}{A^2} \left(R_1 + \frac{R_2 + I_s}{1 + CR_2 s + CI_s^2} \right)$$