

# 11-10\_Line\_Integral

November 11, 2021

```
[2]: from sympy import *  
     from sympy import vector
```

```
[3]: R = vector.CoordSys3D('R')
```

```
[4]: F = (R.x * R.y)**2 * R.i + 2 * R.x**3 * R.y / 3 * R.j + R.z * R.k
```

```
[6]: var('t')  
     r1 = t * R.i + t / 2 * R.j + t**2 * R.k  
     r2 = t**2 * R.i + t / 2 * R.j + t * R.k
```

```
[7]: r1_p = diff(r1, t)  
     r2_p = diff(r2, t)
```

```
[8]: r1_p
```

```
[8]:  $\hat{i}_R + \left(\frac{1}{2}\right)\hat{j}_R + (2t)\hat{k}_R$ 
```

```
[9]: r1.coeff(R.i)
```

```
[9]:  $t$ 
```

```
[10]: F.subs(R.x, r1.coeff(R.i))
```

```
[10]:  $(y_R^2 t^2)\hat{i}_R + \left(\frac{2y_R t^3}{3}\right)\hat{j}_R + (z_R)\hat{k}_R$ 
```

```
[11]: def vec_subs(vec1, vec2, coord):  
     return vec1.subs({  
         coord.x: vec2.coeff(coord.i),  
         coord.y: vec2.coeff(coord.j),  
         coord.z: vec2.coeff(coord.k),  
     })
```

```
[12]: vec_subs(F, r1, R)
```

```
[12]:  $\left(\frac{t^4}{4}\right)\hat{i}_R + \left(\frac{t^4}{3}\right)\hat{j}_R + (t^2)\hat{k}_R$ 
```

```
[14]: vec_subs(F, r1, R).dot(r1_p)
```

```
[14]:
```

$$\frac{5t^4}{12} + 2t^3$$

[15]: `integrate(vec_subs(F, r1, R).dot(r1_p), t)`

[15]:  $\frac{t^5}{12} + \frac{t^4}{2}$

[16]: `integrate(vec_subs(F, r1, R).dot(r1_p), (t, 0, 1))`

[16]:  $\frac{7}{12}$

[17]: `integrate(vec_subs(F, r2, R).dot(r2_p), (t, 0, 1))`

[17]:  $\frac{7}{12}$

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