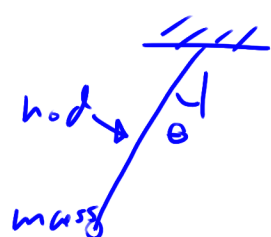


## Loop Efficiency

$$\text{data} = \left[ \begin{array}{c} \vdots \\ \vdots \end{array} \right] \quad \text{random values}$$

find max of data

## Pendulums



$$\frac{d^2\theta}{dt^2} + \frac{g}{l} \sin\theta = 0$$

$$\frac{d^2\theta}{dt^2} = -\frac{g}{l} \sin\theta$$

$$\frac{d\dot{\theta}}{dt} = \frac{d^2\theta}{dt^2}$$

$$\dot{\theta} = \frac{d\theta}{dt}$$

$$\boxed{\frac{d\dot{\theta}}{dt} = -\frac{g}{l} \sin\theta}$$

$$\lim_{\Delta t \rightarrow 0} \frac{f(t+\Delta t) - f(t)}{\Delta t} = \frac{d}{dt} f(t)$$

if  $\Delta t$  small

$$\frac{f(t+\Delta t) - f(t)}{\Delta t} \approx \frac{d}{dt} f(t)$$

$$\frac{\theta(t+\Delta t) - \theta(t)}{\Delta t} = \frac{d\theta}{dt}$$

$$\theta(t+\Delta t) - \theta(t) = \Delta t \dot{\theta}$$

$$\boxed{\theta(t+\Delta t) = \theta(t) + \Delta t \dot{\theta}}$$

$$\frac{\dot{\theta}(t+\Delta t) - \dot{\theta}(t)}{\Delta t} = \frac{d\dot{\theta}}{dt} = -\frac{g}{l} \sin\theta$$

$$\dot{\theta}(t+\Delta t) - \dot{\theta}(t) = \Delta t \left(-\frac{g}{l}\right) \sin\theta$$

$$\boxed{\dot{\theta}(t+\Delta t) = \dot{\theta}(t) - \Delta t \frac{g}{l} \sin\theta}$$

$$\boxed{\begin{bmatrix} \theta \\ \dot{\theta} \end{bmatrix} = \begin{bmatrix} \theta \\ \dot{\theta} \end{bmatrix} + \Delta t \begin{bmatrix} \dot{\theta} \\ -\frac{g}{l} \sin\theta \end{bmatrix}}$$

## Vectorization

$$\begin{bmatrix} \theta_1 \\ \dot{\theta}_1 \\ \theta_2 \\ \dot{\theta}_2 \\ \vdots \end{bmatrix} = \begin{bmatrix} \theta_1 \\ \dot{\theta}_1 \\ \theta_2 \\ \dot{\theta}_2 \\ \vdots \end{bmatrix} + \Delta t \begin{pmatrix} \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix} \begin{bmatrix} \theta_1 \\ \dot{\theta}_1 \\ \theta_2 \\ \dot{\theta}_2 \\ \vdots \end{bmatrix} - \frac{g}{l} \begin{bmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix} \sin \left( \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \end{bmatrix} \right)$$

$$\begin{bmatrix} \theta_1 \\ \dot{\theta}_1 \\ \theta_2 \\ \dot{\theta}_2 \\ \vdots \end{bmatrix} = \begin{bmatrix} \theta_1 \\ \dot{\theta}_1 \\ \theta_2 \\ \dot{\theta}_2 \\ \vdots \end{bmatrix} + \Delta t \left( \underbrace{\begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}}_A \begin{bmatrix} \theta_1 \\ \dot{\theta}_1 \\ \theta_2 \\ \dot{\theta}_2 \\ \vdots \end{bmatrix} - \frac{g}{l} \underbrace{\begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{bmatrix}}_B \sin \left( \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \end{bmatrix} \right) \right)$$